# Lecture 24, Mar 15, 2023

## Magnetic Vector Potential

• We know  $\vec{\nabla} \cdot \vec{B} = 0 \implies \oint_S \vec{B} \cdot d\vec{s} = 0$ – Magnetic flux through a closed surface is always zero

- Magnetic flux is denoted by  $\Phi_m$
- Since the divergence of curl is 0 we can express  $\vec{B}$  as the curl of a potential  $\vec{A}$ 
  - $-\vec{B}$  has units of tesla, or webers per unit area (where weber is the unit of magnetic flux, in volt seconds)
  - $-\vec{A}$  has units of tesla meters, or webers per unit length
  - Note  $\vec{A}$  does not have relation to energy like V does

#### Definition

The magnetic vector potential  $\vec{A}$  is defined such that

$$\vec{B} = \nabla \times \vec{A}$$

It is directly related to the current as

$$\vec{\nabla}^2 \vec{A} = -\mu_0 \vec{J} \implies \vec{A} = \frac{\mu_0}{4\pi} \iiint_V \frac{\vec{J}}{|\vec{R} - \vec{R'}|} \, \mathrm{d}v' = \frac{\mu_0}{4\pi} \int_L \frac{I}{|\vec{R} - \vec{R'}|} \, \mathrm{d}v'$$

which is the analogue of the Poisson equation, where  $\mu_0$  is the magnetic permeability

- Note that the magnetic vector potential is always in the same direction as  $\vec{J}$
- The magnetic flux can be directly determined from the magnetic vector potential:
  - $-\Phi_m = \oint_C \vec{A} \cdot d\vec{l}$  where  $\Phi_m$  is the magnetic flux through any surface with C as its boundary
  - This follows directly from Stokes' theorem

### The Biot-Savart Law

- All magnetic phenomenon come from moving charges (in a permanent magnet, this comes from the movement of charges in the atoms)
- The Biot-Savart law relates magnetic fields to their sources
- Consider a very small bit of current (a current element or filament, which is part of a larger current • loop)
  - This bit of current has position  $\vec{R}'$  and creates a field at  $\vec{R}$

#### Definition

The Biot-Savart law relates the magnetic field intensity to currents:

$$\mathrm{d}\vec{B} = \frac{\mu_0 I \,\mathrm{d}\vec{l} \times (\vec{R} - \vec{R}')}{4\pi |\vec{R} - \vec{R}'|^3}$$

- $I \, \mathrm{d}\vec{l}$  is the analogue of  $\mathrm{d}Q$
- This is completely analogous to Coulomb's law, except for the cross product, which represents the right hand rule
- Given different types of current distributions we can integrate this in different ways to find  $\vec{B}$ :

- Moving charge: 
$$\vec{B} = \frac{\mu_0}{4\pi} \frac{Q\vec{u} \times (R - R')}{|\vec{R} - \vec{R'}|^3}$$

- Linear current loop:  $\vec{B} = \frac{\mu_0}{4\pi} \int_C \frac{I \, \mathrm{d}\vec{l}' \times (\vec{R} \vec{R}')}{|\vec{R} \vec{R}'|^3}$ - Surface current:  $\vec{B} = \frac{\mu_0}{4\pi} \iint_S \frac{\vec{J}_s \times (\vec{R} - \vec{R'})}{|\vec{R} - \vec{R'}|^3} ds'$ - Volume current:  $\vec{B} = \frac{\mu_0}{4\pi} \iiint_V \frac{\vec{J} \times (\vec{R} - \vec{R'})}{|\vec{R} - \vec{R'}|^3} dv'$
- The Biot-Savart law can be derived from A

  e.g. for a strip of length 2a, in the x-y plane extending infinitely in the x direction, the current is  $\vec{J}_s \,\mathrm{d}s' = \frac{I}{2a} \,\mathrm{d}x' \,\mathrm{d}y' \,\hat{a}_x; \text{ find the field at } P(0,0,z)$

$$\begin{aligned} - \mathrm{d}\vec{B} &= \frac{\mu_0 J_s \times (R-R') \,\mathrm{d}s'}{|\vec{R} - \vec{R}'|^3} \\ - & \text{Integrate in } x', y' \text{ since those are the dimensions the strip lives in, } \mathrm{d}s' = \mathrm{d}x' \,\mathrm{d}y' \\ - & \vec{J}_s \,\mathrm{d}s' = \left(\frac{I}{2a}\vec{a}_x\right) \,\mathrm{d}x \,\mathrm{d}y \\ - & \vec{R} = z\vec{a}_z, \vec{R}' = x'\vec{a}_x + y'\hat{a}_y \\ - & \vec{B} = \int_{-\infty}^{\infty} \int_{-a}^{a} \frac{\mu_0 \left(\frac{I}{2a}\right)\hat{a}_x \times (-x'\hat{a}_x - y'\hat{a}_y + z\hat{a}_z)}{4\pi \left(x'^2 + y'^2 + z'^2\right)^{\frac{3}{2}}} \,\mathrm{d}y' \,\mathrm{d}x' \\ &= \frac{\mu_0 I}{8\pi a} \int_{-\infty}^{\infty} \int_{-a}^{a} \frac{-y'\hat{a}_z - z\hat{a}_y}{\left(x'^2 + y'^2 + z'^2\right)^{\frac{3}{2}}} \,\mathrm{d}y' \,\mathrm{d}x' \\ &= -\frac{\mu_0 I}{2\pi a} \tan^{-1} \left(\frac{a}{z}\right) \hat{a}_y \\ * \text{ Note we could ignore the } \hat{a}_z \text{ component because from symmetry and right has } \end{aligned}$$

hand rule we know the field is going to be in the  $-\hat{a}_y$  direction