Lecture 22, Mar 8, 2023

Resistance and Conductance

- Recall that $\vec{J} = \sigma \vec{E}, \vec{E} = \rho \vec{J}$ where σ is the conductivity and ρ is the resistivity, with $\frac{1}{r} = \sigma$
- Resistance and conductance are macroscopic properties that apply to an entire piece of material rather than points within the material
- Using Ohm's law we define resistance as $R = \frac{V}{I}$, conductance as $G = \frac{I}{V} = \frac{1}{R}$
- Consider a material with conductivity σ connected to a battery with voltage V; this creates a field \vec{E} that generates a current \vec{J}

- We know
$$V = -\int \vec{E} \cdot d\vec{l}$$
 and $I = \iint_S \vec{J} \cdot d\vec{s} = \iint_S \sigma \vec{E} \cdot d\vec{s}$ where S is the cross-sectional area
- Therefore $R = \frac{V}{I} = \frac{\left|-\int \vec{E} \cdot d\vec{l}\right|}{C - \vec{D} - \vec{L}}$

- $I \qquad \iint_S \sigma E \cdot d\vec{s}$ Like capacitance, to find the resistance of any material we can assume some voltage and compute how much current this creates, and then take the ratio
- In the case of a simple conductor with uniform S and σ , $V = EL, I = E\sigma S \implies R = \frac{V}{I} = \frac{L}{\sigma S}$
 - For the uniform area conductor we know \vec{E} is constant, because I is constant and therefore \vec{J} must be constant, which leads to \vec{E} being constant
 - This applies to e.g. a cylinder, but not a cone
 - If we don't have uniform cross-sectional area, $R = \int \frac{1}{\sigma S} dl$ where S and σ can be functions of l
 - $\ast\,$ This works even in the case of a non-uniform electric field
 - * Can be thought of as a collection of infinitesimal resistors in series
- Example: resistance of a coaxial cable filled with dielectric ε_r
 - Use Gauss's law to find $\vec{E} = \frac{\rho_{sa}a}{2} \hat{a}_r$

$$-R = \frac{\left|\int \vec{E} \cdot d\vec{l}\right|}{\iint_{S} \sigma \vec{E} \cdot d\vec{s}} = \frac{\left|\int \frac{\rho_{saa}}{\varepsilon_{r}\varepsilon_{0}r} dr\right|}{\int_{0}^{2\pi} \int_{0}^{L} \frac{\sigma \rho_{saa}}{\varepsilon_{r}\varepsilon_{0}a} a \, dz \, d\phi} = \frac{\ln \frac{b}{a}}{2\pi L\sigma}$$

- When we're evaluating the bottom integral to find current, we can choose any surface; usually we choose one so that $\vec{J} \cdot d\vec{s}$ is easy to evaluate (e.g. a Gaussian surface)
 - * We only need to integrate over a single surface, in this case a cylinder of radius a
- We can also find this by $R = \int \frac{1}{\sigma S} dl = \int \frac{1}{\sigma \cdot 2\pi rL} dr$
- Note this assumes that the electric field is uniform down the wire; if the wire were extremely long we would need to consider how \vec{E} changes as you move down the wire, due to resistance of the conductor and leakage current through the dielectric

Joule's Law (Power Loss)

- Since current is the result of the electric field doing work on the electrons, the electric field has to do work to create current
- Power is lost as heat in the system
- Consider an electric field causing a current $\vec{J} = \sigma \vec{E}$ in a non-perfect dielectric; how much power does it take to sustain this current?
 - Consider a very small region; the charges move at the drift velocity

$$-\Delta P = \frac{\mathrm{d}\Delta U}{\mathrm{d}t} \text{ and } \Delta U = W_e \text{ so } \Delta P = \frac{\mathrm{d}}{\mathrm{d}t} \int \vec{F_e} \cdot \mathrm{d}\vec{l} = \frac{\mathrm{d}}{\mathrm{d}t} \int Q\vec{E} \cdot \mathrm{d}\vec{l} = \frac{\mathrm{d}}{\mathrm{d}t} \int \rho_v \Delta v\vec{E} \cdot \mathrm{d}\vec{l}$$
$$-\Delta P = \int \rho_v \Delta v\vec{E} \cdot \frac{\mathrm{d}\vec{l}}{\mathrm{d}t} = \vec{E} \cdot \vec{J}\Delta v$$

Definition

Joule's law:

$$P = \iiint_V \vec{E} \cdot \vec{J} \, \mathrm{d}V$$

relates energy losses in a conductor to the current and electric field in it