

# Lecture 10, Oct 10, 2023

## D'Alembert's Principle

- Consider an inertially fixed point  $O_{\mathcal{J}}$ , an inertially moving point  $O$  and a grammar of particles  $\mathcal{P}_i$ , with positions  $\underline{r}_i$  relative to  $O_{\mathcal{J}}$  and  $\underline{\rho}_i$  relative to  $O$
- How can we accommodate Newton's second law in a noninertial frame?
- $\underline{r}_i = \underline{r}^{O_{\mathcal{J}}} + \underline{\rho}_i$
- The equations of motion are  $m_i \underline{r}_i^{\ddot{\cdot}} = \underline{f}_{i,ext} + \sum_j \underline{f}_i^j = m_i(\underline{\rho}_i^{\ddot{\cdot}} + \underline{r}^{O_{\mathcal{J}}\ddot{\cdot}})$ 
  - Let  $\underline{a}_O = \underline{r}^{O_{\mathcal{J}}\ddot{\cdot}}$  which is the acceleration of  $O$  with respect to  $O_{\mathcal{J}}$
  - $m_i \underline{\rho}_i^{\ddot{\cdot}} = \underline{f}_{i,ext} + \sum_i \underline{f}_i^j - m_i \underline{a}_O$
  - Therefore  $m \underline{\rho}_{\bullet}^{\ddot{\cdot}} = \underline{f} - m \underline{a}_O$
  - Let  $\underline{\pi}_i = m_i \underline{\rho}_i^{\dot{\cdot}}$  be the momentum as seen in  $O$
  - $\underline{\pi} = m \underline{\rho}_{\bullet}^{\dot{\cdot}}$
  - Therefore  $\underline{\pi}^{\dot{\cdot}} = \underline{f} - m \underline{a}_O$
  - Notice that the rate of change momentum as observed in  $O$  is the total force, plus a reversed inertial force
- For the angular momentum:  $\underline{\eta}_i = \underline{\rho}_i \times \underline{\pi}_i$ 
  - The total momentum is then  $\underline{\eta}_0 = \sum_i m_i \underline{\rho}_i \times \underline{\rho}_i^{\dot{\cdot}}$
  - $\underline{\eta}_0^{\dot{\cdot}} = \sum_i \underline{\rho}_i \times (m_i \underline{\rho}_i^{\ddot{\cdot}}) = \sum_i \underline{\rho}_i \times \left( \underline{f}_{i,ext} + \sum_j \underline{f}_i^j - m_i \underline{a}_O \right)$
  - $\underline{\eta}_0^{\dot{\cdot}} = \underline{\tau}_O - \left( \sum_i m_i \underline{\rho}_i \right) \times \underline{a}_O = \underline{\tau}_O - m \underline{\rho}_{\bullet} \times \underline{a}_O = \underline{\tau}_O + \underline{\rho}_{\bullet} \times (-m \underline{a}_O)$

### Definition

D'Alembert's principle: The classical laws of mechanics can be applied in a linearly accelerating frame if reversed inertial forces are applied to the center of mass of a grammar of particles.

## The Rocket Problem

- Consider a rocket with mass  $m$  moving at velocity  $\underline{v}$ ; if  $\underline{f} = \underline{p}^{\dot{\cdot}}$ , then do we have  $\underline{f} = \dot{m} \underline{v} + m \underline{v}^{\dot{\cdot}}$ , since the mass is changing for the rocket?
  - The problem is that we failed to consider the part of the mass that was ejected
- At time  $t$ , the rocket has mass  $m$  and velocity  $\underline{v}$ ; at time  $t + dt$ , the rocket has mass  $m + dm$  and velocity  $\underline{v} + d\underline{v}$ , where  $-dm$  is the amount of mass that was ejected at a velocity  $\underline{v} + \underline{v}_{ex}$
- $\underline{f} = \frac{d\underline{p}}{dt} \implies d\underline{p} = \underline{f} dt = \underline{p}(t + dt) - \underline{p}(t)$ 
  - $\underline{p}(t) = m \underline{v}$
  - $\underline{p}(t + dt) = (m + dm)(\underline{v} + d\underline{v}) + (-dm)(\underline{v} + \underline{v}_{ex})$
  - Under a first order approximation, this reduces to  $d\underline{p} = m d\underline{v} - \underline{v}_{ex} dm = \underline{f} dt$
  - Therefore  $m \frac{d\underline{v}}{dt} - \underline{v}_{ex} \frac{dm}{dt} = \underline{f} \implies m \underline{v}^{\dot{\cdot}} = \underline{f} + \dot{m} \underline{v}_{ex}$
- Comparing this result to what we have before, the difference is that instead of  $-\underline{v}_{ex}$ , in our first incorrect result we had  $\underline{v}$
- Example: consider an open-top railway car with mass  $m_0$  and velocity  $v_0$ , which is collecting rain at a rate  $\dot{m}$ ; what is the velocity of the car after a given time, where an amount of rain  $m$  has fallen?
  - Suppose there is an amount of water  $m$  in the car at time  $t$ , then  $p(t) = (m_0 + m)v$  and  $p(t + dt) = (m_0 + m + dm)(v + dv)$

- Since the rain is falling vertically,  $p(t) = p(t + dt) \implies (m_0 + m)v = (m_0 + m + dm)(v + dv)$
- $v dm + (m_0 + m)dv = 0 \implies \frac{dv}{v} = -\frac{dm}{m_0 + m}$  with initial conditions  $m = 0, v = v_0$  at  $t = 0$
- Integrating both sides:  $\ln \frac{v}{v_0} = -\ln \frac{m_0 + m}{m_0} \implies v = v_0 \frac{m_0}{m_0 + m} \implies (m_0 + m)v = m_0 v_0$
- Example: if the car is dripping so that the water level stays the same, what is the velocity now?
  - $p(t) = m_0 v$
  - $p(t + dt) = m_0(v + dv) + (v + dv)dm$  where  $-dm$  is the amount of water falling out
  - Again  $p(t + dt) - p(t) = 0 \implies m_0 dv + v dm = 0 \implies \frac{dv}{v} = -\frac{dm}{m_0} \implies \ln \frac{v}{v_0} = -\frac{m}{m_0} \implies v = v_0 e^{-\frac{m}{m_0}}$