

Lecture 23, Mar 11, 2022

Vector Derivatives and Integrals

- The derivative of a vector function is defined as $\vec{f}'(t) \equiv \lim_{h \rightarrow 0} \frac{\vec{f}(t+h) - \vec{f}(t)}{h}$
- Derivative can be taken componentwise: $\vec{f}'(t) = f_1'(t)\hat{i} + f_2'(t)\hat{j} + f_3'(t)\hat{k}$
 - Proof:
$$\begin{aligned}\vec{f}'(t) &= \lim_{h \rightarrow 0} \frac{\vec{f}(t+h) - \vec{f}(t)}{h} \\ &= \lim_{h \rightarrow 0} \left[\frac{f_1(t+h) - f_1(t)}{h} \hat{i} + \frac{f_2(t+h) - f_2(t)}{h} \hat{j} + \frac{f_3(t+h) - f_3(t)}{h} \hat{k} \right] \\ &= \lim_{h \rightarrow 0} \frac{f_1(t+h) - f_1(t)}{h} \hat{i} + \lim_{h \rightarrow 0} \frac{f_2(t+h) - f_2(t)}{h} \hat{j} + \lim_{h \rightarrow 0} \frac{f_3(t+h) - f_3(t)}{h} \hat{k} \\ &= f_1'(t)\hat{i} + f_2'(t)\hat{j} + f_3'(t)\hat{k}\end{aligned}$$
- Integrals can also be defined componentwise as $\int_a^b \vec{f}(t) dt = \left(\int_a^b f_1(t) dt \right) \hat{i} + \left(\int_a^b f_2(t) dt \right) \hat{j} + \left(\int_a^b f_3(t) dt \right) \hat{k}$
- All ordinary derivative and integral properties apply:
 - $\int_a^b \vec{c} \cdot \vec{f}(t) dt = \vec{c} \cdot \int_a^b \vec{f}(t) dt$
 - $\left\| \int_a^b \vec{f}(t) dt \right\| \leq \int_a^b \|\vec{f}(t)\| dt$

Differentiation Formulas

- Define a composition function $(\vec{f} \circ u)(t) = \vec{f}(u(t))$
 - Note this composition can't go the other way around, because \vec{f} takes in a scalar and u takes in a vector, so $u(\vec{f}(t))$ makes no sense
- Differentiation rules:
 - $(\vec{f} + \vec{g})'(t) = \vec{f}'(t) + \vec{g}'(t)$
 - $(\alpha \vec{f})'(t) = \alpha \vec{f}'(t)$
 - $(u\vec{f})'(t) = u(t)\vec{f}'(t) + u'(t)\vec{f}(t)$
 - $(\vec{f} \cdot \vec{g})'(t) = \vec{f}(t) \cdot \vec{g}'(t) + \vec{f}'(t) \cdot \vec{g}(t)$
 - $(\vec{f} \times \vec{g})'(t) = \vec{f}(t) \times \vec{g}'(t) + \vec{f}'(t) \times \vec{g}(t)$
 - Note that for this one, order matters since cross product is non-commutative
 - $(\vec{f} \circ u)'(t) = u'(t)\vec{f}'(u(t))$
- Example: $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$
 - Define $r \equiv \|\vec{r}\| = \sqrt{\vec{r} \cdot \vec{r}} = \sqrt{x^2 + y^2 + z^2} \implies \vec{r} \cdot \vec{r} = r^2$
 - $\vec{r} \cdot \vec{r} = r^2 \implies \frac{d\vec{r}}{dt} \cdot \vec{r} + \vec{r} \cdot \frac{d\vec{r}}{dt} = 2r \frac{dr}{dt} \implies \vec{r} \cdot \frac{d\vec{r}}{dt} = r \frac{dr}{dt}$
- Example: $\frac{d}{dt} \frac{\vec{r}}{r}$
 - This is a unit vector in the direction of \vec{r} ; even though the magnitude is constant, the derivative can be nonzero since the direction can change

$$\begin{aligned}
-\frac{d}{dt} \frac{\vec{r}}{r} &= \frac{1}{r} \frac{d\vec{r}}{dt} - \frac{1}{r^2} \frac{dr}{dt} \vec{r} \\
&= \frac{1}{r^3} \left(r^2 \frac{d\vec{r}}{dt} - r \frac{dr}{dt} \vec{r} \right) \\
&= \frac{1}{r^3} \left((\vec{r} \cdot \vec{r}) \frac{d\vec{r}}{dt} - \left(\vec{r} \cdot \frac{d\vec{r}}{dt} \right) \vec{r} \right) \\
&= \frac{1}{r^3} \left(\left(\vec{r} \times \frac{d\vec{r}}{dt} \right) \times \vec{r} \right)
\end{aligned}$$

* Note we used the relationship $(\vec{a} \times \vec{b}) \times \vec{c} = (\vec{c} \cdot \vec{a})\vec{b} - (\vec{c} \cdot \vec{b})\vec{a}$

Curves

- $\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$
- The derivative $\vec{r}'(t)$ is interpreted geometrically as a vector pointing in the tangent direction of the curve
- Definition: Let C be parameterized by $\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$ and be differentiable; then $\vec{r}'(t) = x'(t)\hat{i} + y'(t)\hat{j} + z'(t)\hat{k}$ (if not $\vec{0}$) is tangent to C at $(x(t), y(t), z(t))$ and $\vec{r}'(t)$ points in the direction of increasing t
- Example: Find tangent to $\vec{r}(t) = (1 + 2t)\hat{i} + t^3\hat{j} + \frac{t}{2}\hat{k}$ at $(9, 64, 2)$
 - First find the t value: $\vec{r}(4) = (9, 64, 2)$
 - $\vec{r}'(t) = 2\hat{i} + 3t^2\hat{j} + \frac{1}{2}\hat{k} \implies \vec{r}'(4) = 2\hat{i} + 48\hat{j} + \frac{1}{2}\hat{k}$
 - The tangent line is $\vec{R}(q) = 9\hat{i} + 64\hat{j} + 2\hat{k} + q \left(2\hat{i} + 48\hat{j} + \frac{1}{2}\hat{k} \right)$
- Define the *unit tangent vector* as $\vec{T}(t) \equiv \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$
 - Note $\vec{T}(t) \cdot \vec{T}(t) = 1$ since \vec{T} is a unit vector
 - Differentiating this leads to $\vec{T}'(t) \cdot \vec{T}(t) = 0$
 - $\vec{T}'(t)$ is always in the perpendicular direction to \vec{T} ; this is because \vec{T} has a constant magnitude so the derivative can only represent a change in direction, which is always perpendicular
 - $\vec{T}'(t)$ is telling you the direction that the curve is curving, similar to how the second derivative tells you whether the function is concave up or down

Arc Length

- Extended to 3D, arc length is $\int_a^b \sqrt{(x'(t))^2 + (y'(t))^2 + (z'(t))^2} dt = \int_a^b \|\vec{r}'(t)\| dt$
- Example: Circular helix $\vec{r}(t) = 3 \sin(t)\hat{i} + 3 \cos(t)\hat{j} + 4t\hat{k}$ for $t \in [0, 2\pi]$
 - $\vec{r}'(t) = 3 \cos(t)\hat{i} - 3 \sin(t)\hat{j} + 4\hat{k}$
 - $\|\vec{r}'(t)\| = \sqrt{9 \cos^2 t + 9 \sin^2 t + 16} = 5$
 - $\int_0^{2\pi} \pi \|\vec{r}'(t)\| dt = 10\pi$
- Sometimes a curve is parameterized with respect to arc length instead of t
- Example: $\vec{r}(t) = t^2\hat{i} + t^2\hat{j} - t^2\hat{k}$ from $(0, 0, 0)$
 - $s = \int_0^t \|\vec{r}'(\tau)\| d\tau$
 - $= \int_0^t \sqrt{4\tau^2 + 4\tau^2 + 4\tau^2} d\tau$
 - $= \int_0^3 2\sqrt{3}\tau d\tau$
 - $= \sqrt{3}t^2$

$$- s = \sqrt{3}t^2 \implies t^2 = \frac{s}{\sqrt{3}} \implies \vec{r}(s) = \frac{s}{\sqrt{3}}\hat{i} + \frac{s}{\sqrt{3}}\hat{j} - \frac{s}{\sqrt{3}}\hat{k}$$