Lecture 7, Sep 22, 2022

Simple Pendulum

- $-mg\sin(\theta) = L\frac{\mathrm{d}^2\theta}{\mathrm{d}t^2}$
- Under a small angle approximation $-\frac{g}{L}\theta = \frac{d^2\theta}{dt^2}$ In this case "small" means < 10°
- $\theta(t) = \theta_{max} \sin(\omega t + \theta_0), \omega^2 = \frac{g}{L}, T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{L}{q}}$
- For any arbitrary object, we can use the centre of mass point and pivot point and the moment of inertia $-\theta(t) = \theta_{max}\sin(\omega t + \theta_0)$

$$-\omega^2 = \frac{mg}{r}$$

- Even though m appears in the equation, the frequency does not actually depend on mass since it cancels with the m term in I

Coupled Oscillators

• Consider two pendulums with masses m_A , m_B connected by a spring with constant k

Normal Modes

Definition

A normal mode is a mode of oscillation where every mass is oscillating at the same frequency and fixed phased relation

- Consider 2 cases:
 - Displacing them the same amount $x_A = x_B$
 - * In this case the springs are unstretched; both masses oscillate in phase with the same frequency

$$\omega_1 = \sqrt{\frac{g}{L}}$$

- Displacing them in opposite directions $x_A = -x_B$
 - * Assuming masses are the same, then $m_A \frac{d^2 x_A}{dt^2} = -\frac{mg}{L} x_A 2kx_A$ The masses are stretched by the same amount, so the total spring stretch is $2x_A$
 - * Both masses oscillate with frequency $\omega_2 = \sqrt{\frac{g}{L} + \frac{2k}{m}}$
 - * The masses are out of phase
- These are the *normal modes* of oscillation
 - "Normal" since they are linearly independent

Superposition of Normal Modes

- In general $x_A \neq \pm x_B$
- Assume the angles are small so the spring is horizontal
 Restoring force on m_A is ^{mg}/_L x_A k(x_A x_B), force on m_B is ^{mg}/_L x_B + k(x_A x_B) This gives us a system of coupled differential equations
- Adding the two equations shows SHM with variable $x_A + x_B$ and frequency $\omega = \sqrt{\frac{g}{L}}$

• Subtracting the two equations shows SHM with variable $x_A - x_B$ and frequency $\omega = \sqrt{\frac{g}{L} + \frac{2k}{m}}$ - The $\frac{2k}{m}$ term represents the coupling

• Let $x_A + x_B = q_1, x_A - x_B = q_2$, then $q_1(t) = C_1 \cos(\omega_1 t + \phi_1), q_2(t) = C_2 \cos(\omega_2 t + \phi_2)$ where $\omega_1 = \sqrt{\frac{g}{L}}, \omega_2 = \sqrt{\frac{g}{L} + \frac{2k}{m}}$ • Energy is $E = \frac{1}{2}m\left(\frac{\mathrm{d}x_A}{\mathrm{d}t}\right)^2 + \frac{1}{2}m\left(\frac{\mathrm{d}x_B}{\mathrm{d}t}\right)^2 + \frac{1}{2}\frac{mg}{L}(x_A^2 + x_B^2) + \frac{1}{2}k(x_A - x_B)^2$

$$= \frac{1}{4}m\left(\frac{\mathrm{d}q_1}{\mathrm{d}t}\right)^2 + \frac{1}{4}\frac{mg}{L}(q_1)^2 + \frac{1}{4}m\left(\frac{\mathrm{d}q_2}{\mathrm{d}t}\right)^2 + \frac{1}{4}\left(\frac{mg}{L} + 2k\right)(q_2)^2$$