# Lecture 6, Sep 19, 2022

# **Existence and Uniqueness of Solutions**

• Given an ODE, does a solution exist, and is the solution unique?

### Theorem

Given  $y' + p(t)y = g(t), y(t_0) = y_0$ , and p, g continuous over  $t_0 \in (\alpha, \beta)$ , then there exists a unique solution in the interval  $(\alpha, \beta)$ 

#### Theorem

Given  $y' = f(t, y), y(t_0) = y_0$ , and  $f, \frac{\partial f}{\partial y}$  continuous over  $(t_0, y_0) \in (\alpha, \beta) \times (\gamma, \delta)$ , then there exists a unique solution in **some** interval  $(t_0 - h, t_0 + h) \in (\alpha, \beta)$ 

The existence (but not uniqueness) of a solution can be established on the continunity of f alone



Figure 1: Visualization of the first-order nonlinear existence and uniqueness theorem

- The first-order nonlinear existence and uniqueness theorem only guarantees the existence and uniqueness of a solution in some interval within h, which we don't know
  - The linear version guarantees the entire continuous interval, whereas the nonlinear version only guarantees some smaller interval within the continuous interval
- Examples:

$$-y' + \frac{2}{t}y = 4t, y(1) = 2$$

\* Use the linear theorem

\* p, g continuous except where t = 0

\* The initial condition lies within the continuous region, so a unique solution exists for  $t \in (0, \infty)$  $\frac{dy}{dt} = \frac{3t^2 + 4t + 2}{2}, \quad u(0) = -1$ 

$$\frac{dy}{dt} = \frac{dy}{2(y-1)}, y(y)$$

- \* Use the nonlinear theorem
- \* f is continuous except where y = 1
- \*  $f_y$  is continuous except where y = 1
- \* The initial condition lies in the region of continuity, so a unique solution exists for some region  $t \in (-h, h)$

$$-\frac{\mathrm{d}y}{\mathrm{d}t} = \frac{3t^2 + 4t + 2}{2(y-1)}, y(0) = 1$$

- \* Since f is not continuous at the initial condition, the theorem does not apply
- $\ast\,$  Even though it's not guaranteed that a solution will exist, a solution may still exist
- \* Solving the DE does yield a solution, but the solution is not unique

## Important

Implication: The graphs of two solutions cannot intersect each other where the theorems hold (because this would violate the uniqueness of solutions)

"Just because you can't see a solution to an ODE doesn't mean you can't prove it exists." – Vardan, MAT292 (2022)