

## Lecture 9, Oct 13, 2021

### Proving Trig Identities Using Matrices

- Rotation matrix:  $T_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$
- Define the composition  $T_\theta(T_\theta(\vec{v})) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} \cos^2 \theta - \sin^2 \theta & -2 \sin \theta \cos \theta \\ 2 \sin \theta \cos \theta & \cos^2 \theta - \sin^2 \theta \end{bmatrix}$
- Since  $T_\theta(T_\theta(\vec{v})) = T_{2\theta} = \begin{bmatrix} \cos 2\theta & -\sin 2\theta \\ \sin 2\theta & \cos 2\theta \end{bmatrix}$  but  $T_\theta(T_\theta(\vec{v})) = \begin{bmatrix} \cos^2 \theta - \sin^2 \theta & -2 \sin \theta \cos \theta \\ 2 \sin \theta \cos \theta & \cos^2 \theta - \sin^2 \theta \end{bmatrix}$ , we can conclude 
$$\begin{cases} \sin 2\theta = 2 \sin \theta \cos \theta \\ \cos 2\theta = \cos^2 \theta - \sin^2 \theta \end{cases}$$

### Eigenvalues & Eigenvectors

- Certain vectors do not change direction (remain parallel) when transformed by a linear transformation; they are the *eigenvectors* of that transformation, and the amount they are scaled by are the *eigenvalues*
- $A\vec{v} = \lambda\vec{v}$ , where  $\vec{v}$  is an eigenvector and  $\lambda$  is an eigenvalue
- Example: For a transformation that projects every vector onto a fixed vector, every vector parallel to the fixed vector is an eigenvector of the transformation with eigenvalue 1; every vector orthogonal to it is an eigenvector of the transformation with eigenvalue 0
- The number of eigenvalues (note: these can be complex) is always the same as the dimension of the matrix (note: nonsquare matrices don't have eigenvalues)
- To find eigenvectors, note  $A\vec{v} = \lambda\vec{v} \implies A\vec{v} - \lambda\vec{v} = 0 \implies A\vec{v} - \lambda I\vec{v} = 0 \implies (A - \lambda I)\vec{v} = 0$ , so the eigenvectors are the null space of  $A - \lambda I$ 
  - Note that this null space is only nontrivial if  $\det(A - \lambda I) = 0$ , so we can find eigenvalues by finding the values of  $\lambda$  that make  $\det(A - \lambda I) = 0$